PackOS: A Microkernel Based on IPv6

Master's thesis by John Stracke

Introduction

- The core of any microkernel is its IPC.
- Most microkernels use some sort of RPC.
- PackOS uses IPv6 instead.

Why would you do that?

- Reuse the existing IP-based protocols.
- Communicate with outside world.
- Simplify the kernel.
- IPv6 instead of IPv4 because of address space.
 - Each process needs an address.

Benefits

- All kernel calls are O(1).
 - No outstanding kernel operations.
 - No kernel stacks, which means cheap threads.
- Simplifies process migration.
 - All resources identified by IPv6 address.
 - Copy the memory space, use Mobile IP to deliver.
 - Notify process to start using local resources.

Prior work

- The main influence on PackOS was L4.
- L4 has RPC-based IPC.
 - Partially zero-copy.
 - Structured messages.
 - Clans & Chiefs.
 - Overcomplicated.

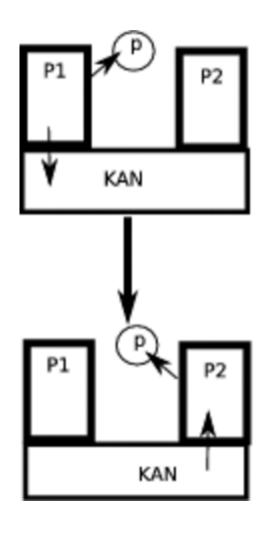
What PackOS learned from L4.

- IPC performance is vital.
 - Slow IPC means large-grain components.
 - Large-grain components limit flexibility.
- L4 features PackOS adopted:
 - Zero-copy.
 - User-space process management.
 - User-space drivers.

PackOS's innovation: the KAN

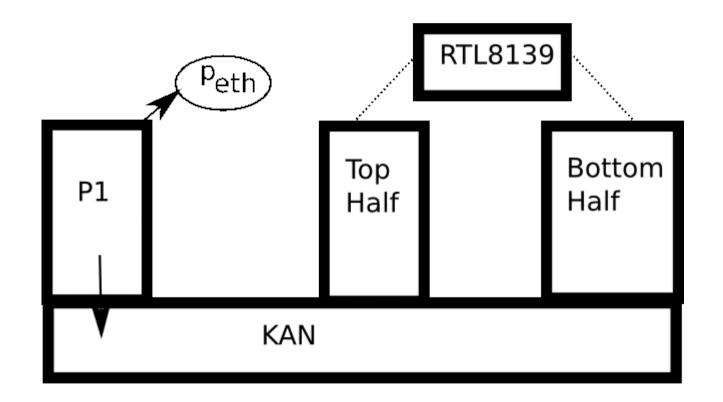
- Kernel Area Network: a virtual link layer.
- Asynchronous IPC.
- Packets are pages.
 - Mapped out of sender's space, into recipient's.
 - Zero-copy.
- Every process has at least one KAN address.
- Network interfaces are routers.

Zero-copy IPC

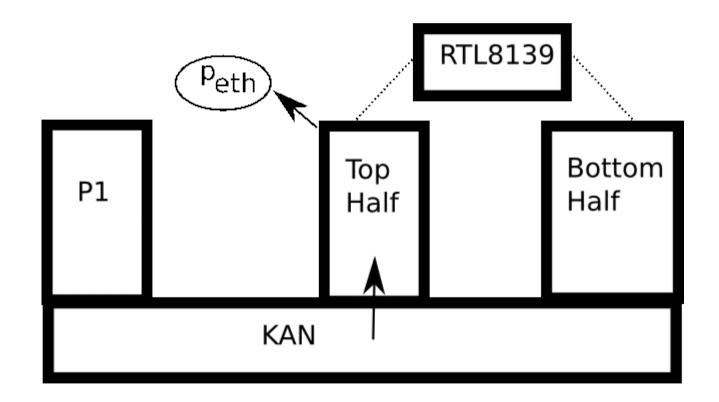


The KAN (continued)

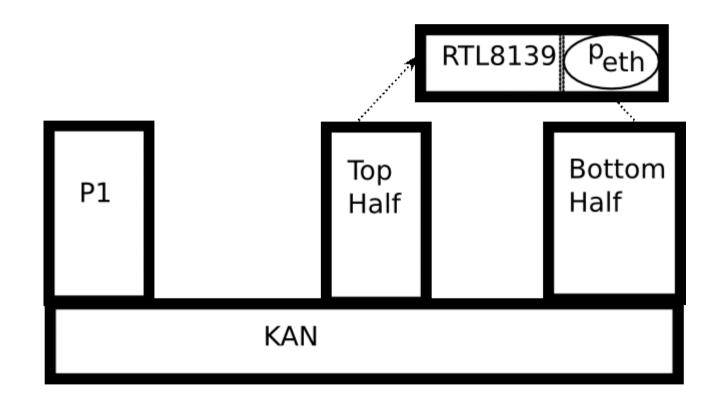
- Finds unusual uses.
- Interrupt handling via IPC.
 - User space driver requests interrupt notification.
 - On each interrupt, a KAN packet is delivered to the bottom half.
 - Bottom half manages the hardware, sends packet to top half; kernel clears interrupts.
 - Top half talks to other processes.



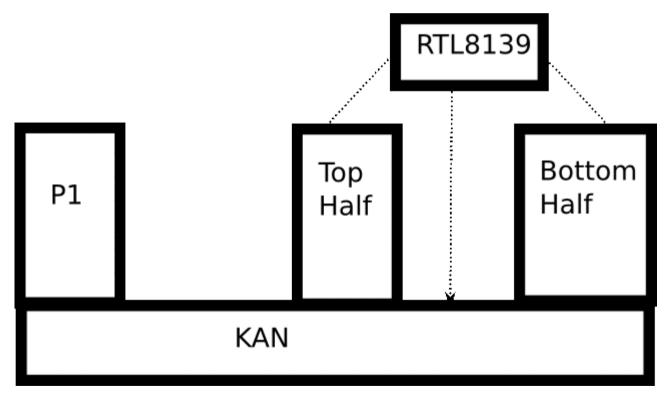
P1 prepares a packet to send over Ethernet.



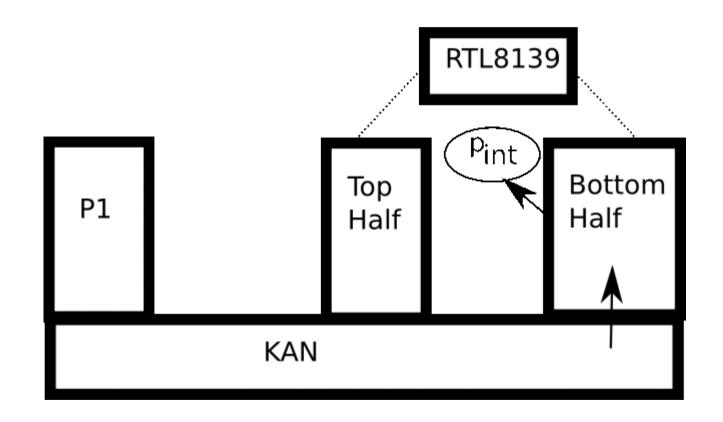
The top half receives the packet.



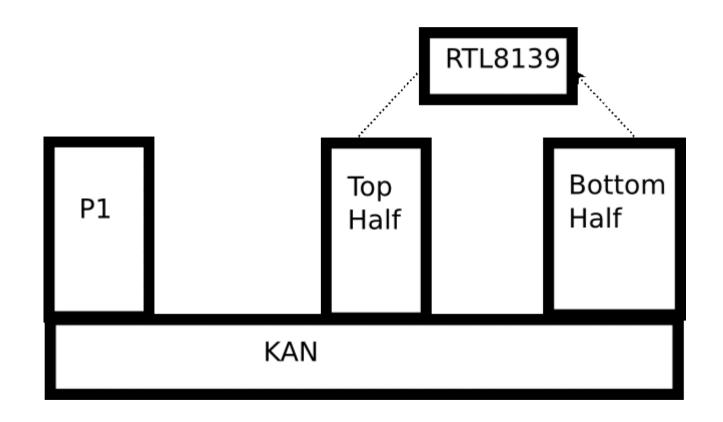
The top half copies the packet into the NIC.



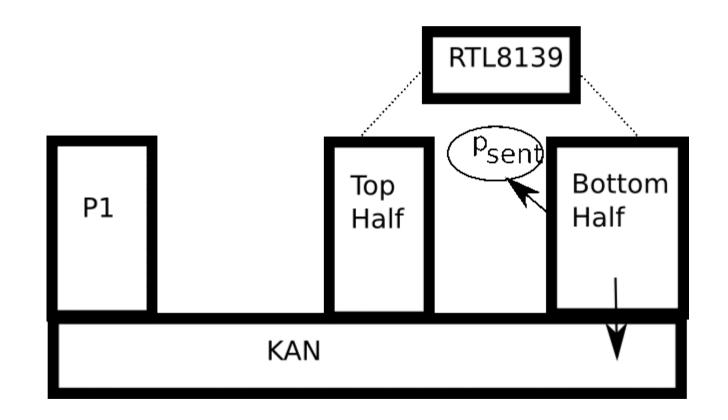
When the packet has been sent, the NIC raises an interrupt.



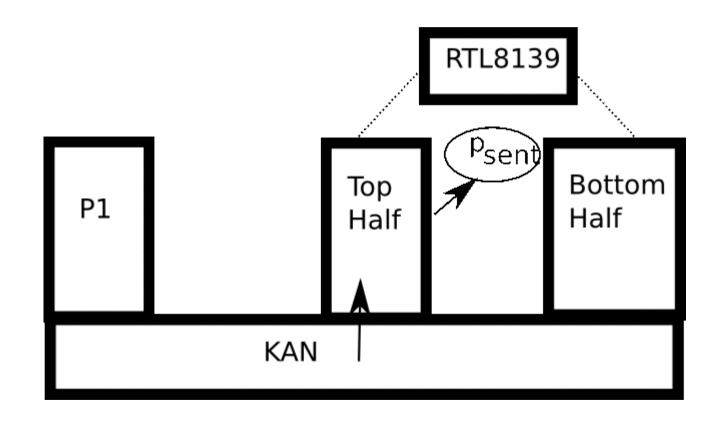
The kernel sends the bottom half an interrupt packet.



The bottom half updates the NIC data structures.



The bottom half sends a packet to notify the top half.



The top half updates its internal data structures.

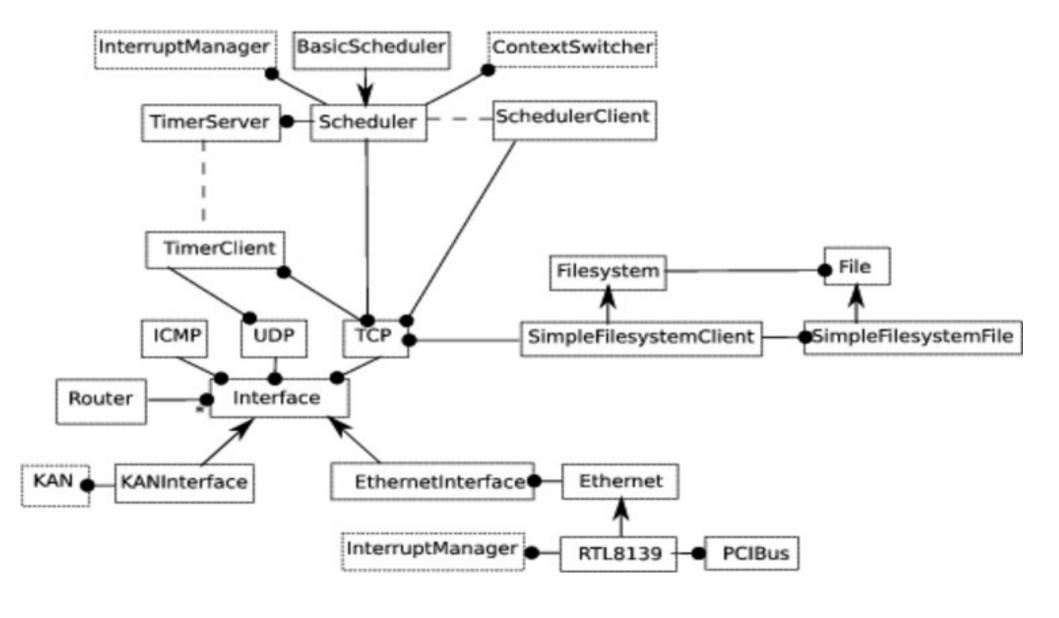
The prototype

- Started as a semester project in 91.516, running under Linux, in user space.
- Later ported to x86 PC hardware.
 - Started in real mode, moved to protected kernel.
- Adding memory protection among processes uncovered flaws in user space code.
 - Accidental use of globals spanning processes.

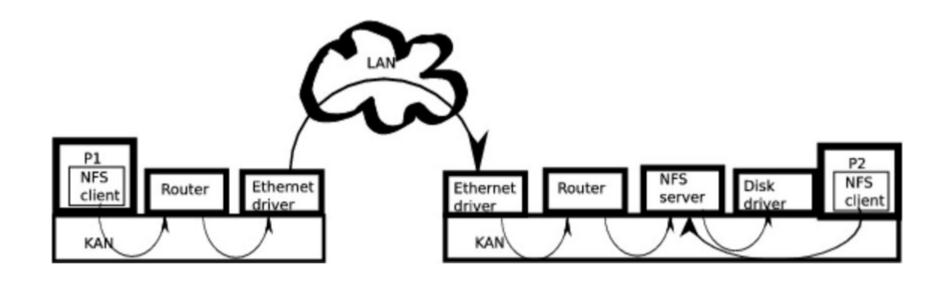
The prototype (2)

- Solving the prototype's flaws proved impractical.
- A new design is needed.
- Learned lessons from the prototype.
- These lessons will inform the new design.

The prototype: classes

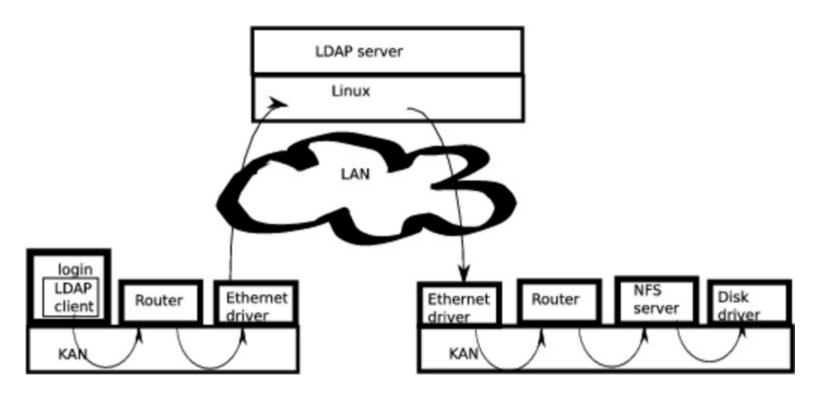


Interaction example



Two PackOS systems. The right-hand system is running an NFS server, which is being used by processes P1 and P2. Arrows show client-to-server direction.

Heterogeneous example



A heterogeneous network including two PackOS systems and one Linux system. The left-hand PackOS system is using the Linux system's LDAP server for authentication; the LDAP server is using the right-hand PackOS system's NFS server for its configuration files.

Lessons learned

- Include memory protection from the start.
- Separate user and kernel binaries.
- PackOS needs threads.
- DMA is dangerous.
- The kernel should include a clock.

Include memory protection from the start.

- Original user-space prototype could not have memory protection.
- All processes were into the same binary.
- Certain crucial libraries had state crossing process boundaries.
- Once memory protection was added, large amounts of user-space code needed to be rewritten.

Separate user and kernel binaries.

- In the prototype, all is in the same executable.
- Reasonable for original user-space implementation.
- A problem in protected mode: no compile-time separation between kernel code and user code.
- In the new design, PackOS should have separate binaries from the start.
 - Bootstrap in kernel, ELF in user space.

PackOS needs threads.

- In the prototype, all processes are singlethreaded.
- Event-driven loop.
- Unreasonably difficult to work with.
- New design will permit multithreaded processes.

DMA is dangerous.

- A design goal: keep device drivers from touching anything but their assigned hardware.
- Not possible with most DMA-capable hardware: DMA bypasses the MMU.
- Long-standing problem, much research behind it. Requires new hardware designs.
- New design can't solve it, but should be aware of the problem.

DMA is dangerous.

• "I don't have any solution, but I certainly admire the problem." — Ashleigh Brilliant

The kernel should include a clock.

- In general, interrupts are handled in user space.
- For the clock interrupt, this turns out to be prohibitively expensive.
- In the prototype, the scheduler handles clock interrupts.
- But other code (esp. TCP) needs ticks.

The kernel should include a clock.

- User-space library for asking the scheduler for ticks.
- Much too slow, though.
- Solution: put ticks into kernel, with referencecounted packets.
 - Reference-counted packets needed for multicast anyway.

Result: New design

- Full details of the new design are in my thesis.
- A summary of the interesting decisions:
 - Threads.
 - IPv6 interface objects.
 - Per-process filesystems.
 - Service discovery.
 - Requires multicast.

New design: Threads

- Kernel provides context switching and packet delivery.
- Many-to-many relationship between contexts and KAN endpoints will permit threading.
- Useful for implementing TCP: a separate thread can handle all TCP traffic and deliver results to other threads in same process.

New design: Threads (2)

- Will require in-process synchronization primitives.
- Don't want to add them to the kernel; don't want to incur latency of round trip to a lock server.
- Can be implemented via atomic operations, plus the ability to yield to another thread.

New design: IPv6 interface objects

- An interface is an object to send and receive packets.
- Subclasses present in the prototype: KAN interface, Ethernet interface.
- Most processes have just one interface, for the KAN.
- Routers have two or more interfaces.

New design: Per-process filesystems.

- Most filesystems accessed over the KAN.
 - Each process has its own filesystem clients.
- No reason all the processes have to access the same file servers.
- Similar to Plan 9.
 - Possibly at a finer grain, though: different code in same process might access different file servers.

New design: Service discovery.

- Based on DNS SRV records.
- Want to find a local server that offers filesystem X? Ask for corresponding SRV record.
- Probably via multicast DNS (aka zeroconf, Rendezvous).
 - Prototype doesn't have multicast, so...

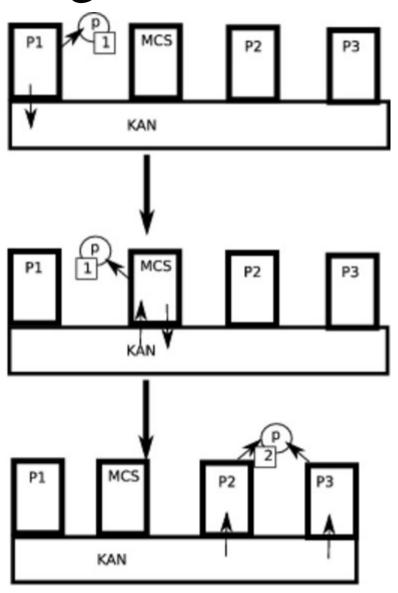
New design: Multicast

- Various possibilities.
- Most of them involve giving up the O(1) guarantee and/or zero-copy networking.
- Two remaining options:
 - Multicast server.
 - Multicast KAN endpoints.
- Both require reference counting on the packets.

New design: Multicast server

- Processes would talk to the multicast server, asking to join and leave multicast groups.
- To send a multicast packet, send it to the server.
 - Server address at link layer, group address at IP layer.
- Server forwards.
- Disadvantages:
 - Latency.
 - Single point of failure.

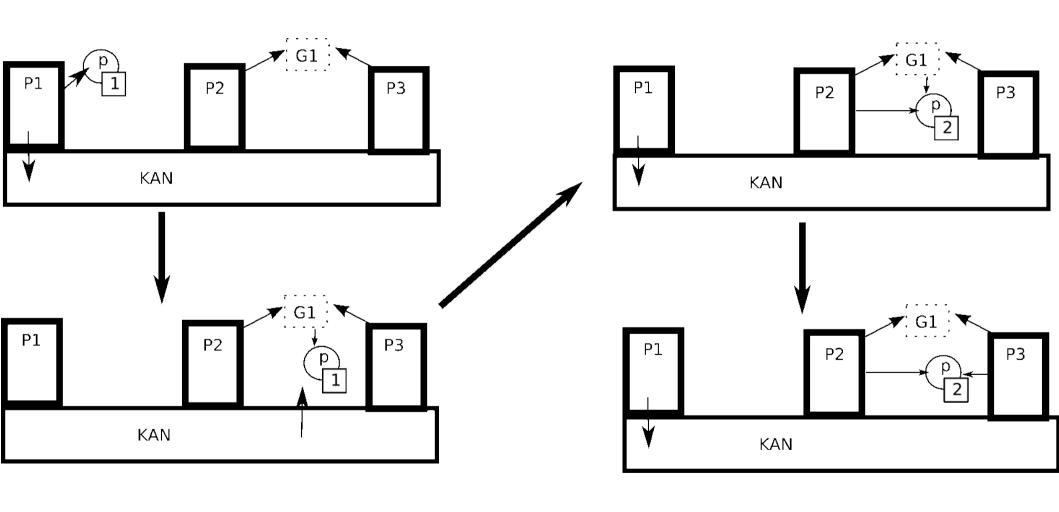
New design: Multicast server



New design: Multicast KAN endpoints

- Requires kernel support.
- Join/leave groups by asking the kernel.
- Any group with members has a KAN endpoint.
 - Circular buffer of packets for the group.
- If endpoint X is a member of group G, then receiving on X checks G's queue first.

Multicast KAN endpoints



Conclusion

- The prototype was a limited success.
- Functioning OS:
 - TCP/IPv6
 - Ethernet
 - HTTP server
- Provided plenty of experience for version 2.

Future work

- Process migration.
- POSIX support.
- Hardware support.
- Performance comparisons.
- Flexibility exploration.